Installation

Packing List

1. Connect the HAT’s MIPI_TX0 port to Raspberry Pi’s camera port.

Turn off your Raspberry Pi and disconnect the power supply.
2. Connect the Quad-Camera HAT.

3. Connect the 4 camera modules to the Rx ports.

4. Power your Raspberry Pi on.
Operating The Camera

The camera requires a driver to be installed according to the platform in use, please see the following.

**for Raspberry Pi**
https://docs.arducam.com/Raspberry-Pi-Camera/Multi-Camera-CamArray/quick-start/

**for NVIDIA Jetson**
https://docs.arducam.com/Nvidia-Jetson-Camera/Multi-Camera-CamArray/quick-start/
Instructions for Safe Use

To properly use the Arducam quad-camera kit, kindly note:

- Before connecting, you should always power the Raspberry Pi off and remove the power supply first.
- Make sure the cable on the camera board is locked in place.
- Make sure the cable is correctly inserted in the Raspberry Pi board’s MIPI CSI-2 connector. Avoid high temperatures.
- Avoid water, moisture, or conductive surfaces while in operation.
- Avoid folding, or straining the flex cable.
- Avoid cross-threading with tripods.
- Gently push/pull the connector to avoid damaging the printed circuit board.
- Avoid moving or handling the printed circuit board excessively while it’s in operation.
- Handle by the edges to avoid damages from electrostatic discharge.
- Where the camera board is stored should be cool and as dry as possible.
- Sudden temperature/humidity changes can cause dampness in the lens and affect the image/video quality.