



# Raspberry Pi Multi Camera Adapter Module User Guide

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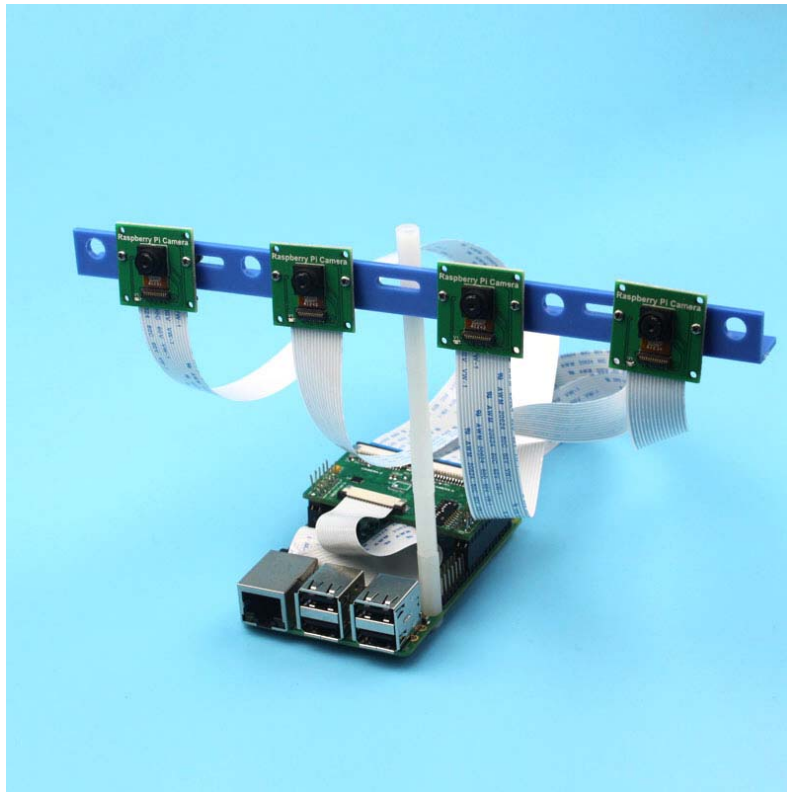
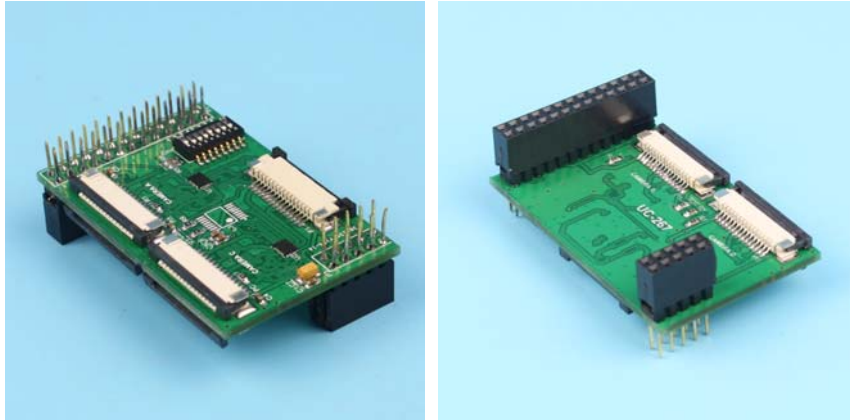


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## 1 Introduction

Raspberry Pi multi camera adapter module is designed for connecting more than one camera to a single CSI camera port on Raspberry Pi board. One adapter board can connect 4 cameras and user can stack up maxim 4 adapter boards that means up to 16 cameras on a single Raspberry Pi board. Please note that Raspberry Pi multi camera adapter board is nascent product that may have some stability issues and limitations because of the cable's signal integrity and RPi's closed source video core libraries, so use it on your own risk.

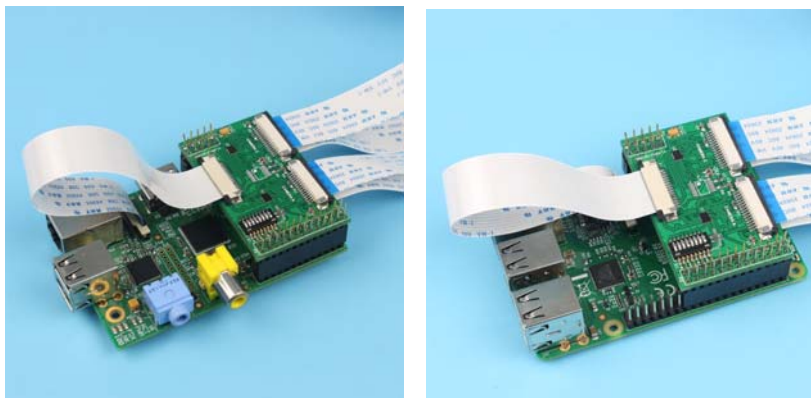


## 2 Application

- IoT cameras
- Robot cameras
- Wildlife cameras
- 3D scanner

## 3 Features

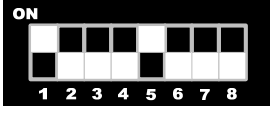
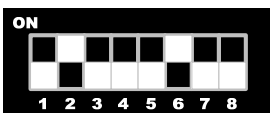
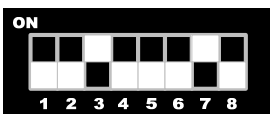
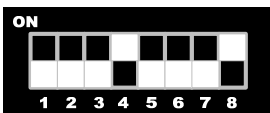
- Accommodate 4 Raspberry Pi cameras on an multi camera adapter board
- Stackable and maxim cascade 4 adapter boards
- 3 GPIOs required for multiplexing on one adapter board, 5 GPIOs for two adapter board, 9 GPIOs for four adapter board
- All camera ports are FFC (flexible flat cable) connectors
- DIP switches for easy stack up configuration
- Support Raspberry Pi A/B/B+ and Pi 2.



## 4 Pin Configuration

DIP switches are used here for easy stack up configuration. When only one multi camera adapter board is used, the switches 1 and 5 should be switched to ON position. If two multi camera adapter boards are used, the downside board should be switched 1 and 5 to ON and upside board should be switched 2 and 6 to ON position, and if 3 or 4 multi camera adapter boards are used together each board layer should be configured as the Table 1 shown. The PinX indicates the pin number on the Raspberry Pi’s main GPIO connector.

Table 1 Pin Configuration

Stacking Layer	Selection	Enable 1	Enable 2	DIP Switch Configuration
1	Pin 7	Pin 11	Pin 12	
2	Pin 7	Pin 15	Pin 16	
3	Pin 7	Pin 21	Pin 22	
4	Pin 7	Pin 23	Pin 24	

## 5 Operation

For proper operation, only one camera should be enabled at a time. In case of only one multi camera adapter board is used, driving Pin 12 HIGH and driving Pin 11, Pin 7 to LOW to enable camera A on the adapter board. Enable camera B, C and D, please refer the Table 2 for camera selection configuration. To disable all cameras on one adapter board, Enable 1 and Enable 2 signals should be toggled HIGH. Care should be taken that it is not allowed to drive the Enable 1 and Enable 2 LOW at the same time. When connecting more than two multi camera adapter boards, only one of the cameras can be enabled by enabling the desired camera on one adapter board, and disable all the cameras on the rest of adapter boards.

Table 2 Camera Selection Configuration

Camera Selection Configuration	Selection	Enable 1	Enable 2
A	0	0	1
B	1	0	1
C	0	1	0
D	1	1	0
No Camera	X	1	1
Error	X	0	0

(X: don't care)

## 6 Software Demonstration

Before using it, required dependency python - rpi.gpio have to be installed with `sudo apt - get install python - rpi.gpio` command from the Terminal. Then run the following code from Appendix A for the quick demo.

As normal camera operation, user can still use `raspistill` or `raspivid` command to take photos or videos. By control the GPIOs according to the Table 1 and Table 2 configuration, user can take photos or videos by switching between different cameras. Have funs!

## 7 Appendix A Demo Code

```
import RPi.GPIO as gp
import os

gp.setwarnings(False)
gp.setmode(gp.BOARD)

//Setup the stack layer 1 board
gp.setup(7, gp.OUT)
gp.setup(11, gp.OUT)
gp.setup(12, gp.OUT)

// Setup the stack layer 2 board if any
gp.setup(15, gp.OUT)
gp.setup(16, gp.OUT)
// Setup the stack layer 3 board if any
gp.setup(21, gp.OUT)
gp.setup(22, gp.OUT)
// Setup the stack layer 4 board if any
gp.setup(23, gp.OUT)
gp.setup(24, gp.OUT)

//Disable stack layer 1 board output
gp.output(11, True)
gp.output(12, True)
//Disable stack layer 2 board output
gp.output(15, True)
gp.output(16, True)
//Disable stack layer 3 board output
gp.output(21, True)
gp.output(22, True)
//Disable stack layer 4 board output
gp.output(23, True)
```

```
gp.output(24, True)

def main():
    gp.output(7, False)
    gp.output(11, False)
    gp.output(12, True)
    capture(1)

    gp.output(7, True)
    gp.output(11, False)
    gp.output(12, True)
    capture(2)

    gp.output(7, False)
    gp.output(11, True)
    gp.output(12, False)
    capture(3)

    gp.output(7, True)
    gp.output(11, True)
    gp.output(12, False)
    capture(4)

def capture(cam):
    cmd = "raspistill -o capture_%d.jpg" % cam
    os.system(cmd)

if __name__ == "__main__":
    main()

    gp.output(7, False)
    gp.output(11, False)
    gp.output(12, True)
```